

Army Robotics at the Tactical Edge





Unclassified



AGENDA





Unclassified

RRD Mission and Purpose

Enabling Lethality and Improving Survivability Through Disciplined Innovation & Focused Integration

MISSION

RRD, in coordination with key stakeholders, will enable the Army to deliver robotics that enables our Army to Fight and Win and Dominate in a Multi-Domain environment by 2030.

VISION

We will *drive requirements* and *drive transitions* in order to deliver AI enabled robotics that is expeditionary, integrated, hardened, and intuitive that enables the lethality of our Warfighters to dominate in any environment, anytime and anywhere.



PRIORITIES

Meeting Army Senior Leader Priorities & Combatant Commander Requirements

- People- Talent Management
- Process- Learning Organization; Improve Everyday
- Products- Professional, Timely, and accurate
- PPBE- Align Resources to Deliver Capability

Drive Requirements

Threat Informed

Market Research

Science & Technology

Continuous Evolution & Refinement of Operational Requirements

Experimentation & Demonstration

Test & Evaluation

Drive Transitions

"As we move into the Future...a Soldier should never be the first to make contact with the Enemy..." - GEN Kurilla

RRD <u>narrows assigned</u>
<u>Army Capability gaps</u> using
DOTMLPF-P enhancements
to enable overmatch, while
continually informing
Stakeholder enterprise
across the Army, Joint
services, Coalition Partners,
Defense Laboratories,
Industry, and Academia

RRD informs technology transitions, research and development, and user assessments, and then rapidly transitions operational requirements for procurement in support of our Nations Warfighters

RRD integrates and synchronizes robotic activities across the Army, tied to joint requirements, bolstered by Stakeholder enterprise information, with focused effort to improve speed, capability, cost effective, and state-of-the-art material solutions

RRD will engage in expert analysis, focused experiments, technology demonstrations and gather meaningful Soldier feedback to inform and drive innovation and transition well developed and refined capability documentation



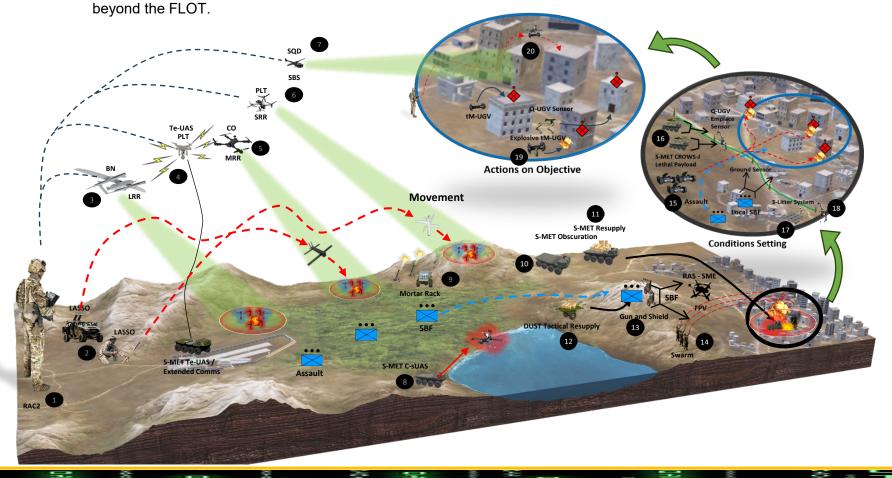
"New equipment without integration is just fielding kit and not capability ..." – GEN James E. Rainey, AFC Commanding General



HMI-IBCT OV-1



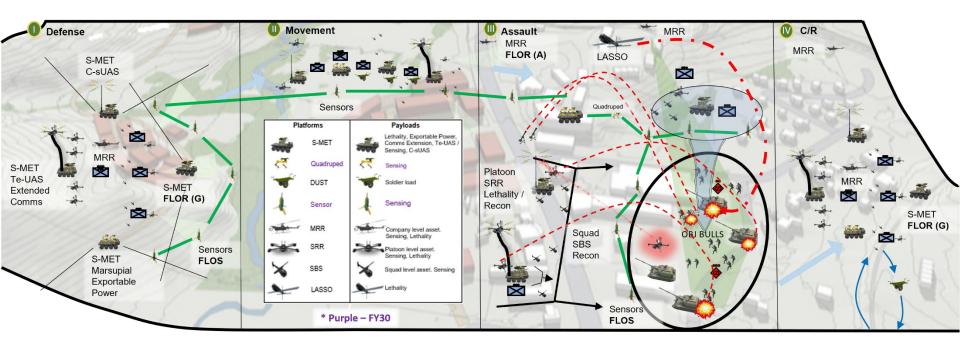
Robotic Enabled Maneuver at the Tactical Edge: Equipped with ground Robotic Autonomous Systems (RAS), which are integrated as part of a layered network of sensors and shooters, the Infantry Soldier provides leaders a sense, detect, and identification capability at extended range. This will enhance situational awareness and increase decision space to employ organic or higher headquarters effects (lethal and non-lethal) with precision to shape the battlefield. "Close with and Destroy" remains fundamental to the Light Infantry Formation. Robotic Enabled Maneuver provides the ability to gain and maintain contact





"A Way" for HMI Light Employment







Key Tasks FY23 Rollup



Air Key tasks:

- Nano SBS: Expected staffing in 1QFY25
- SRR: Projected down select late FY24
- Swarm: FY23 Market research led to AEWE 2024 submission
- > Te-UAS: Staffing projected NLT 3QFY24
- MRR: Supported through approved Co-Lv UAS Directed Requirement for Tranche 1
- LRR: Currently in Army Staffing

Ground Key Tasks:

- > SMET INC 2/MMP Development: Approved Requirement in August 2023; RFP released to Industry
- Electric Lightweight Transport, AKA Dismounted Unit Soldier Transport (DUST) in development process
- RAC2: Merged technical approach with SCI for Uncrewed Vehicle Control (UVC)efforts; SRR Tranche 2 Will be the first platform with RAC2 software

Al Key Tasks:

- > 10X 23/24 Trust: Campaign of Experiments to integrate AI and Robotic capabilities into a maneuver force and to inform Robotic Enabled Maneuver ICD
- Launched Effects: Family of systems under MTA Rapid Prototyping Effort, Medium Range A-CDD approved May 2020, Short-Range Moving to AROC with A-CDD next month.

C-sUAS Key Tasks:

- Dismounted capability: in development with partnership with AMD-CFT
- Mounted Capability: in development with partnership with AMD-CFT
- Munitions Ballistic PROX/DE, EW: Working with joint community on existing technologies for kinetic capability
- UAV vs. UAV: Working with industry partners on several variations of this capability (EW, kinetic and pneumatic)
- > Passive vs. Active Detect: System limitations and lessons learned are being analyzed for consideration for future
- C2 data Transport: Supporting PM efforts to move to an application-based capability



J-sUAS Modular Mission Payloads: Future



FLOS

BATTALION

Old Req. Documents:

- 1. 2013 Rucksack Portable CPD. Covers RQ-11B/C Raven (Current Co level Medium-Range Reconnaissance capability) & RQ-28A Short-Rane Reconnaissance Tranche 1 2 (Platoon).
- 2. 2017 Soldier Borne Sensor (SBS) CPD (Squad).

New Req. Documents:

- 1. 2023 Joint-small UAS CDD (Officially Signed 13 June 2023). RRD Air Branch writing annexes for: SRR / SBS / MRR / LRR / Te-UAS / Swarm / and FPV.
- 🗕 2. 2023 Company-Level sUAS Army Futures Command Commanding General Directed Requirement (MRR) Will provide initial capability / inform MRR J-sUAS Annex development.
- . 3. 2022 Robotic Autonomous Command & Control (RAC2) Capability Needs Statement. (Software Acquisition Pathway for Common Robotic Control [Air & Ground Robotics]).

(EO/IR, Comms Relay & Network Extension, EW - Sensing (+), Lethality)

The Hunter & Killer Air - Ground Littoral Fight

FŁOT

Swarm

SQUAD 🔀 🖊

4. 2023 Operational Needs Statement for 6-8 CAV Enhanced Ground Reconnaissance Initiative (Te-UAS).

Modular Mission Payloads

5. 2022 Lethal Unmanned Systems (LUS) AFC CG Directed Requirement (J-sUAS = Hunter / LUS = Killer) *Note: Lethal Modular Mission Payloads enable Family of J-sUAS to carry organic "precision strike / attack" capabilities.

Pass Forward capability for

a cooperative engagement

SF SF

COMPANY

J-sUAS CDD Annex LOEs:

- 1. SRR Funded POR
- 2. SBS Funded POR
- 3. LRR Funded POR New Start
- 4. MRR + (Company-Level sUAS Directed Req.)
- 5. Te-UAS New Start
- 6. First Person View (FPV) New Start
- 7. Swarm S&T Effort New Start
-

Note: Annexes are aligned with ACoE UAS GOSC
Approved Realignment

RAS – SME Operator

The Soldier is the "Center of Gravity" on the battlefield for Robotic Enabled Maneuver

PLATOON



Echelonment of sUAS / U.S. Army Strategy / UAS Realignment 2030+



Current Programs of Record 2013 RPUAS CPD / SBS CPD

Future PORs & J-sUAS CDD Lines of Effort 2023 J-sUAS CDD Approval and UAS Realignment with AVCoE

Influencing LOEs to J-sUAS 2024 - 2025

Brigade: RQ-7 Shadow Range: 60 km / 4 hours

Payloads: EO/IR System Cost: \$23m

System Configuration: 4 x Aircraft. 2 x Controller, Ancillary Equipment.

Battalion: None / Capability Gaps

Company: RQ-11 Raven (RPCPD) Range: 10 km / 1.5 hours Payloads: EO/IR System Cost: \$200k System Configuration: 2 x Aircraft.

1 x Controller, Ancillary Equipment.

Platoon: RQ-28A SRR (RPCPD)

Range: 3 km / 30 min Payloads: EO/IR

System Cost: \$45k System Configuration: 2 x Aircraft, 1 x Controller, Ancillary Equipment.

Squad: Black Hornet 3 (SBSCPD)

Range: 1 km / 30 min Payloads: EO/IR

System Cost: \$15k System Configuration: 2 x Aircraft, 1 x Controller, Ancillary Equipment.

System Cost: \$10m System Configuration: 6 x Aircraft, 2 x Controller, Ancillary Equipment,

(FTUAS)

BN: Long Range Reconnaissance (LRR)

Range: 40 km / 5 hours

Range: 125 km / 8 hours

Payloads: EO/IR, Comms Ext, EW-S, Lethality System Cost: \$1.1m

Sys. Configuration: 2 x Aircraft, 2 x Controller, Ancillary Equipment.

Brigade: Future Tactical UAS

Pavloads: EO/IR. Communications Ext.

CO: Medium-Range(MRR)

Range: 10 km / 8 hours per 24-hour period Payloads: EO/IR, Comms Ext, EW-S, Lethality System Cost: \$350k

Sys. Configuration: 2 x Aircraft, 2 x Controller, Ancillary Equipment.



PLT: Short Range (SRR)

Range: 3-5km / 30+ min

Payloads: EO/IR, Comms Ext, Lethality

System Cost: \$40k

Sys. Configuration: 2 x Aircraft, 1 x Controller, Ancillary Equipment.

PLT: Tethered UAS (Te-UAS)

New Start

Range: NA / Persistent Stare Payloads: EO/IR, Comms Ext, EW-Sensing

System Cost: \$200k Sys. Configuration: 1 x Aircraft, 1 x Controller,

SQD - PLT: First Person View (FPV)

New Start

Range: 2km / 30 min Payloads: EO/IR,

Ancillary Equipment.

System Cost: \$3k

Svs. Configuration: 3 x Aircraft, 1 x Controller. Ancillary Equipment.

Co: Swarm (S&T New Start)

New Start

Range: 5km+ / 30 min

Payloads: EO/IR. Lethality System Cost: Unknown

Sys. Configuration: Undetermined

SQD: BH4 Soldier Borne Sensor (SBS)

Range: 2km / 30+ min Payloads: EO/IR. Comms Ext

System Cost: \$16k

Sys. Configuration: 1 x Aircraft, 1 x Controller, Ancillary Equipment.

Company-Level sUAS DR

Informs J-sUAS CDD MRR Annex

Range: 10 km / 8 hours per 24-hour period Payloads: EO/IR, Comms Ext, EW-S,

Lethality

System Cost: \$350k

Sys. Configuration: 2 x Aircraft, 2 x Controller, Ancillary Equipment.



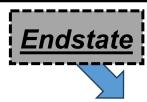
CSA COTS Initiative

Non-Deployable Trainer Range: 3 km / 30 min

Pavloads: EO/IR System Cost: \$25 m

Sys. Configuration: 1 x Aircraft, 1 x Controller, Ancillary Equipment.





JROCM Acceptance Memo



J-sUAS CDD Approved



Co-Level

sUAS DR

LASSO DR Approved



LRR ANNEX 100%



MRR ANNEX Te-UAS ANNEX



Next Gen

SRR ANNEX

85%

Next Gen

SBS ANNEX

90%



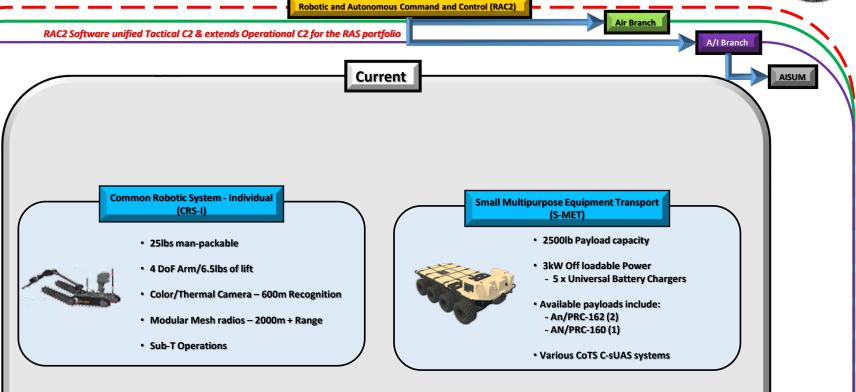






Ground Robotics Branch Path Forward





Payload Development

The RAS portfolio is a family of systems with mutually supporting characteristics across echelons to ensure resilience of the maneuver force



Ground Robotics Branch Path Forward – 2030-2040



AISUM

A/I Branch

Robotic and Autonomous Command and Control (RAC2)

RAC2 Software unified Tactical C2 & extends Operational C2 for the RAS portfolio

2030

Dismounted Unit Soldier Transport (DUST)



- Reduced Soldier Load
- Increased task performance
- Reduce musculoskeletal injuries
- Powered / Passive

Small Multipurpose Transport Inc. II (S-MET Inc. II)

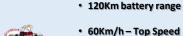


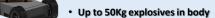
- CDD Approved 4QFY23
- Will be re-competed
- Modular autonomy kit
- Includes MMP Annexes - Autonomy - C-sUAS

 - Distributed Comms
 - Lethality
 - CASEVACG

Consumable Combat Robots (CCR)

2040





10Km NLOS control range

>750m enemy tank visual ID

Legged Robots (Q-UGV)



*Notional

- Active Sensors
- Lethality Packages
- Recon/Surveillance
- Sub-T Operations

*Notional

Payload Development



Platform Autonomy for Complex Environments (PACE)



Purpose: PACE adds autonomous behaviors to the Small Multipurpose Equipment Transport (S-MET) robotic platform to augment dispersed dismounted operations.

Approach: PACE Annex to the approved S-MET CDD for hardware development and experimentation under the MTA pathway and CNS Appendix for embedded software.

Development: PACE establishes detailed user operational requirements to guide S&T development and transition technologies into operationally relevant solutions.

Implementation: Modular Open System Approach (MOSA) strategy includes Army standards (RAS-G IOP v6+) for implementation on other ground robotic platforms.

BLUF – S-MET is the pathfinder that leads to follow-on Autonomous Capability across the ground robotic portfolio

Guide S&T and IRAD investment • Field capability • Transition to other programs



Dispersed Sensors and Low Flying Threats



Detecting, tracking, and identifying threat sUAS requires dispersed capability combined with the range of active sensing.

Passive Radar is necessary and critical, but insufficient:

- Shorter range passive radar combined with other passive sensors (RF, etc) allow at least detection of low flying nearby threat sUAS
- RF and some other passive sensors have very long range but depend on the threat sUAS actively putting out a signature (irrelevant against automated, hardened, or sUAS using nonstandard signal)

Threat sUAS flying high enough to maximize ISR payloads will likely require active sensing to engage unless it has NAVWAR & EW vulnerabilities

Lower altitude threat sUAS will be vulnerable to passive radar, EO/IR tracking, and EW/NAVWAR and ballistic effectors.



- Contest airspace below long-range detection horizon
- Dispersed sensors and effectors throughout formations and echelons allow both self-defense and contribution to larger airspace defense plans
- Can be used in tandem to compliment active sensing



C-sUAS - 2030-2040







Effectors



- Radar (active vs passive)
- RF detection
- EO/IR (SWIR/LWIR)
- - Acoustic
 - Laser designation
 - Hyper spectoral
 - C2 for sensors/effectors and sharing to force



- Ballistics
- Interceptors (kinetic/non-kinetic)
- Rockets/Missiles
- Directed Energy
- EW capabilities (Jam/ NAVWAR)

FoCUS (DR signed 21 Jul

23); OA Inc 2 completed

 Multiple vendors with integration vs stand-alone

28-30 Aug 23

Microwave

*Space Claim and Integration

System and Unit

Integrated Platforms Leading the Development









- ISV/S-MET (IBCT)
- Stryker (SBCT)
- AMPV (ABCT)
- · On-the-Move vs static

*DOTmLPF-P implications

The DCT Collac most con-

The BCT C-sUAS must combine security, protection and counter reconnaissance principles.

2040

C-sUAS Future

 RAS Enabled Initiative to Contest and Overmatch maneuver BCT sUAS airspace to enable freedom of maneuver



- Echeloned and integrated capability that disintegrates the adversary in depth
- MOS agnostic ASI trained leaders and operators
- Network enabled not network dependent
- · Stand off ranges
- Homestation training enabled
- · Fiscally affordable to required numbers
- JCIDS backed requirements derived from MTA experimentation
- LRU modeled modernization
- *Adaptive to an ever changing threat

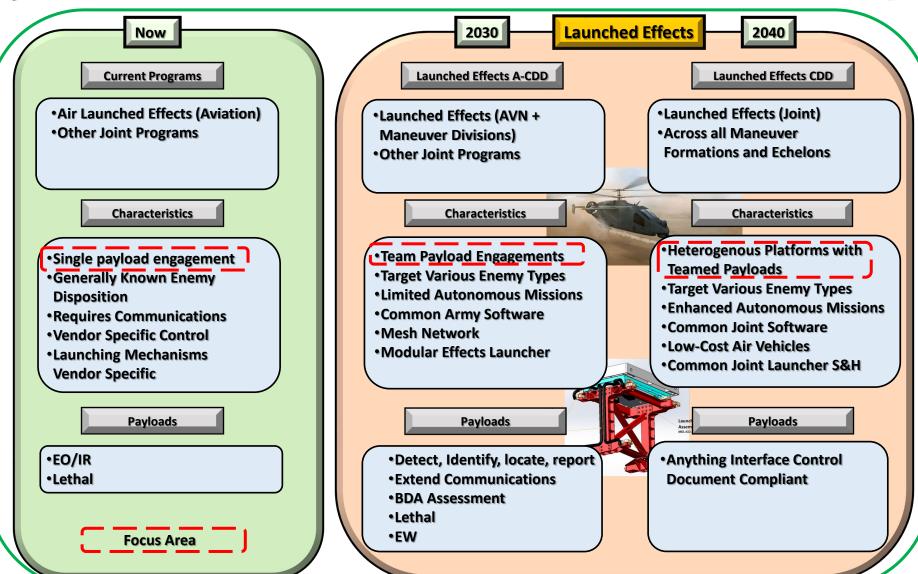


Unclassified



Launched Effects

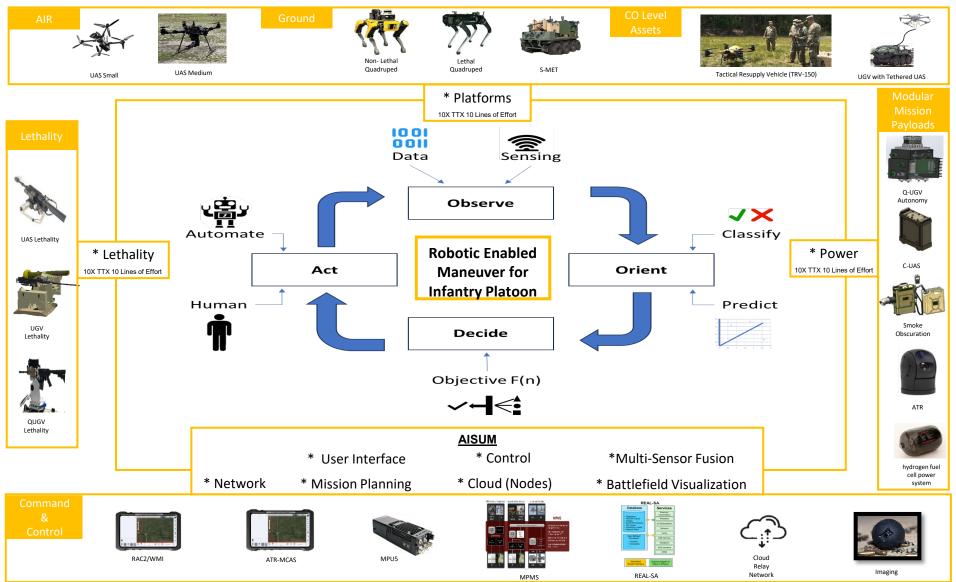






10x Overview







FY 24 Challenges



Air Branch

Swarm Capabilities and Technologies

Ground Branch

- Ground Autonomy
- Payload development

C-sUAS Branch

- Need integrated solutions of sensors and effectors on singular platforms to detect, track, ID, and defeat
- Must be fiscally affordable as proliferation of capability is more important than exquisite
- Operation is MOS agnostic
- Capability hosted on formation appropriate platforms, while core capabilities match across formations
- Capable of integrating with current and future Army C2
- Need for dispersed sensing

AI / 10 X Branch

- Network architecture to support fusion of data centric robotic systems at echelon
- Edge computing
- Affordable approach to maintain AI models and update algorithms with meaningful data to ensure AI
 enabled systems stay relevant on an evolving battlefield.

HMI

Software and Common Control



Meeting with RRD



If you were unable to signup for a one-on-one meeting with RRD for 29 FEB 24, RRD has from 1500-1600 (split into 30 min sessions) every Thursday blocked off to meet with Industry Partners. These can occur in person, on MS Teams, over the phone, or SVTC. If you wish to schedule a meeting, email RRD-MCDID-ASO@army.mil and we will place it on the calendar and confirm the meeting details with you.



Questions?



